

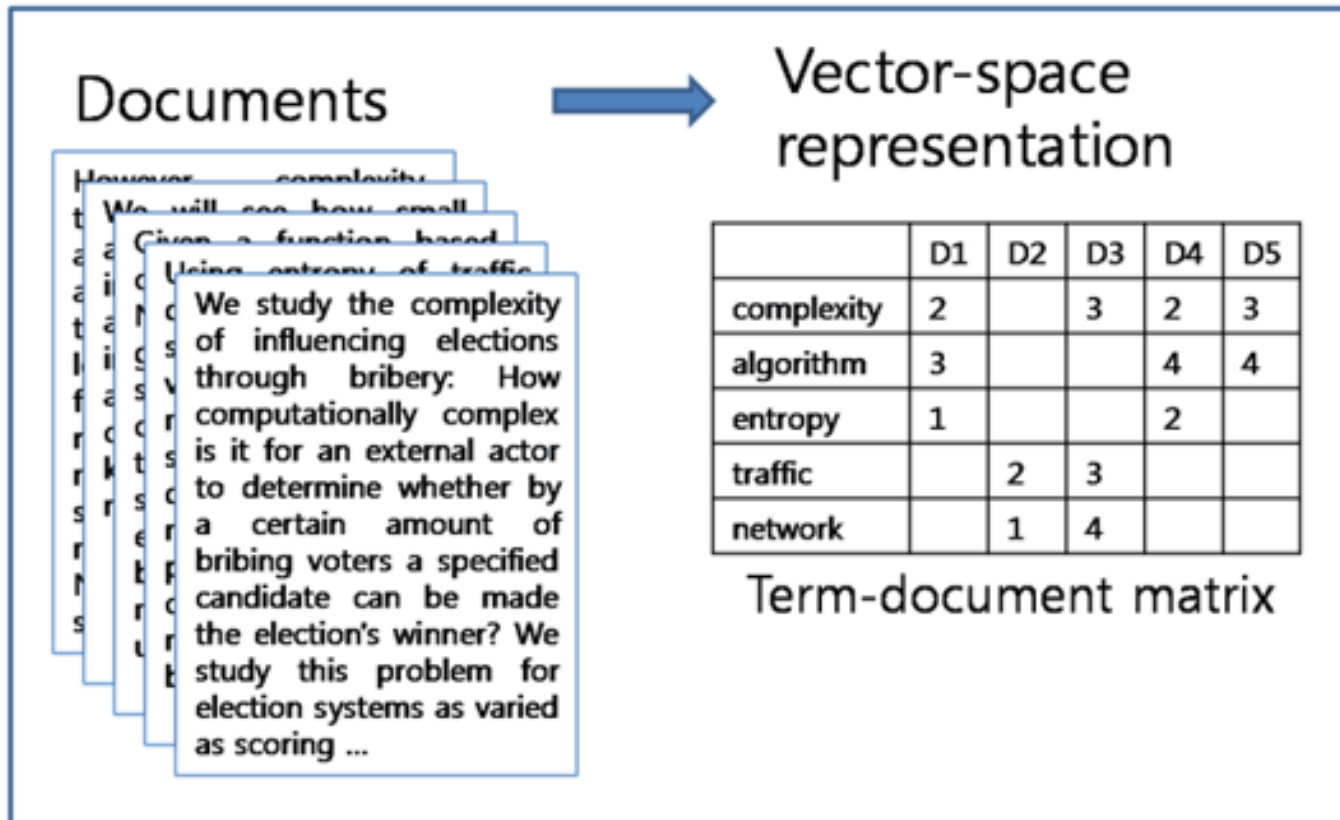


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# Applications of Matrix Factorizations

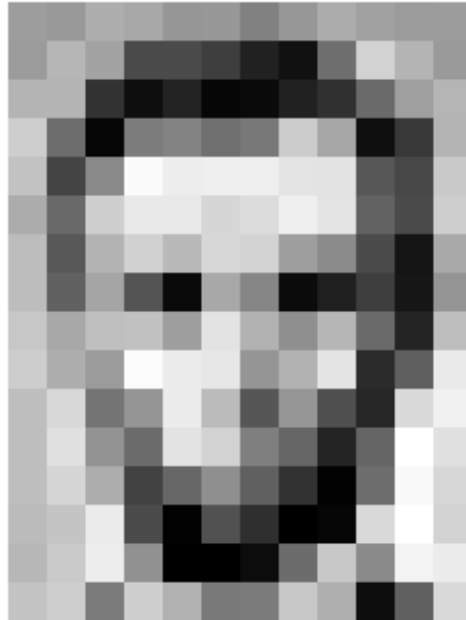
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Lab Sistem Cerdas Online Seminar Series #5  
Thursday, July 30th 2020



**Document-Term Matrix**

# Data Representation



157	153	174	168	150	152	129	151	172	161	155	156
155	182	163	74	75	62	33	17	110	210	180	154
180	180	50	14	34	6	10	33	48	106	159	181
206	109	5	124	191	111	120	204	166	15	56	180
194	68	137	251	237	239	239	228	227	87	71	201
172	106	207	233	233	214	220	239	228	98	74	206
188	88	179	209	185	215	211	158	139	75	20	169
189	97	165	84	10	168	134	11	31	62	22	148
199	168	191	193	158	227	178	143	182	105	36	190
205	174	155	252	236	231	149	178	228	43	95	234
190	216	116	149	236	187	86	150	79	38	218	241
190	224	147	108	227	210	127	102	36	101	255	224
190	214	173	66	103	143	96	50	2	109	249	215
187	196	235	75	1	81	47	0	6	217	255	211
183	202	237	145	0	0	12	108	200	138	243	236
195	206	123	207	177	121	123	200	175	13	96	218

157	153	174	168	150	152	129	151	172	161	155	156
155	182	163	74	75	62	33	17	110	210	180	154
180	180	50	14	34	6	10	33	48	106	159	181
206	109	5	124	131	111	120	204	166	15	56	180
194	68	137	251	237	239	239	228	227	87	71	201
172	106	207	233	233	214	220	239	228	98	74	206
188	88	179	209	185	215	211	158	139	75	20	169
189	97	165	84	10	168	134	11	31	62	22	148
199	168	191	193	158	227	178	143	182	105	36	190
205	174	155	252	236	231	149	178	228	43	95	234
190	216	116	149	236	187	86	150	79	38	218	241
190	224	147	108	227	210	127	102	36	101	255	224
190	214	173	66	103	143	96	50	2	109	249	215
187	196	235	75	1	81	47	0	6	217	255	211
183	202	237	145	0	0	12	108	200	138	243	236
195	206	123	207	177	121	123	200	175	13	96	218

**Color Image Representation in Matrix**

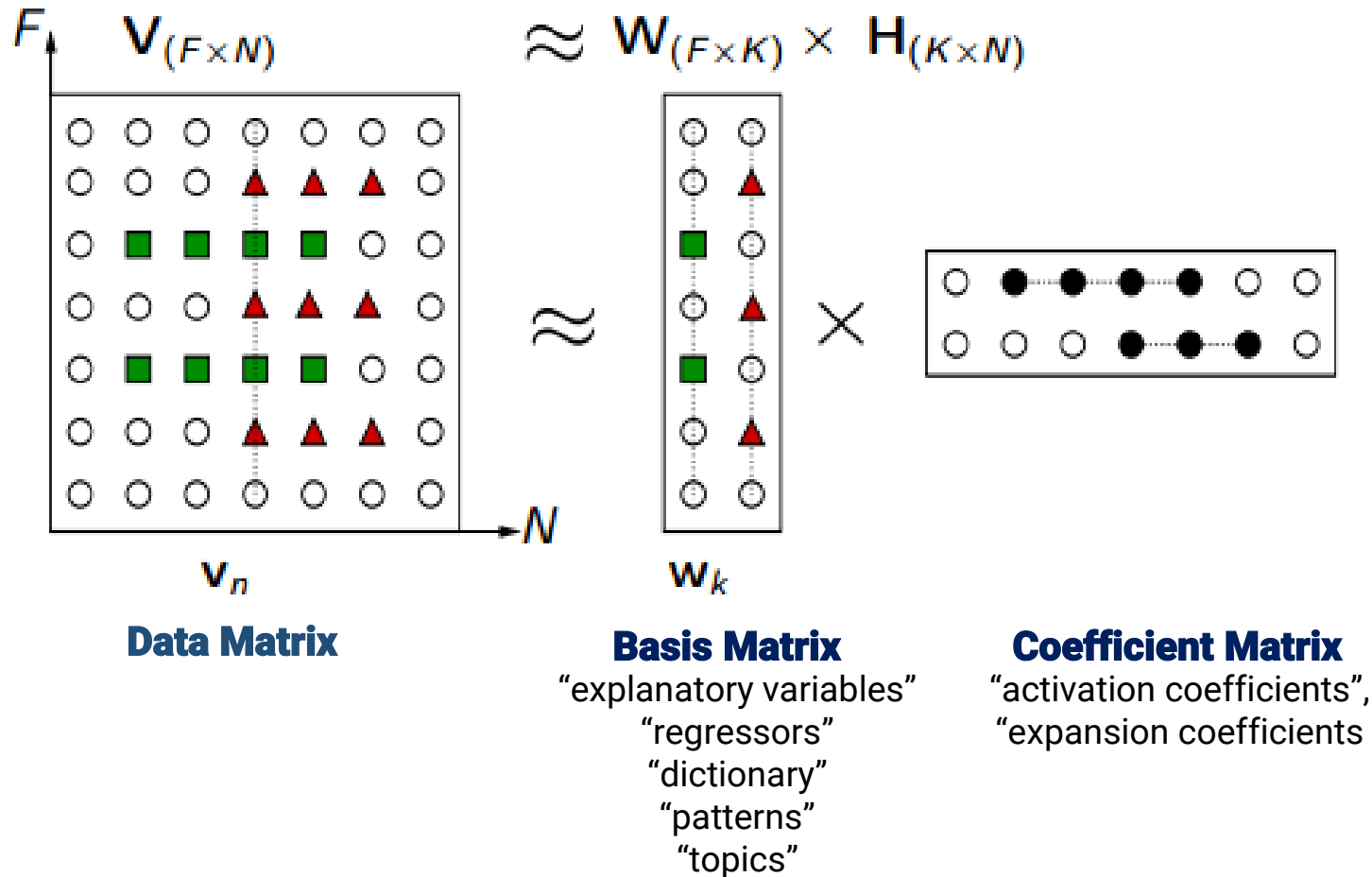


# Dimensionality Reduction

- ❑ Dimensionality reduction is an effective method to represent data by finding factorizations of a matrix.
- ❑ Matrix factorization is one of the methods for dimensionality reduction and it has been applied in many applications.
- ❑ Matrix factorization methods in feature extraction reduce a matrix into constituent parts, that make the algorithm much easier and improve its performance and less computation load.

# Explaining Data by Factorization

## General Formulation



# Matrix Factorization Methods



Principal Component  
Analysis (PCA)

Linear Discriminant  
Analysis (LDA)

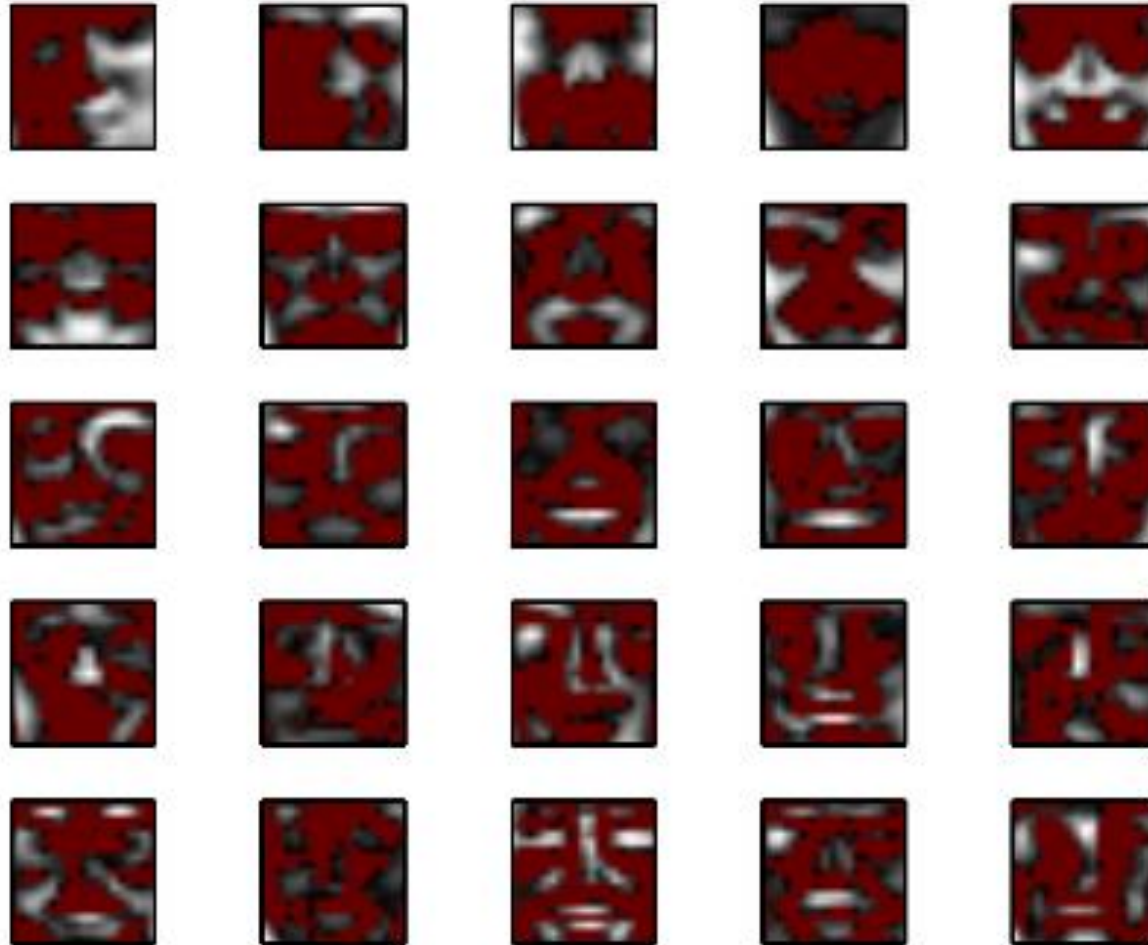
Locally Linear  
Embedding (LLE)

Independent  
Component Analysis  
(ICA)

Partial Least Squares  
(PLS)

# Face Images by PCA

## Eigenfaces



Red pixels indicate **negative values!** How to interpret this?

# In the Real World

Data is always non-negative by nature



- Image pixel intensities
- Signal intensities
- Occurrence counts
- Gene expression data
- User rating scores
- Chemical compound concentration
- Stock market values
- Food or energy consumption
- .....

The **non-negativity constraints** allows the intuitive interpretation as the real understanding of the original data.



# Nonnegative Matrix Factorization

**NMF** aims to find low dimensional approximation to the original matrix using two **nonnegative** matrices



$$V \approx WH;$$

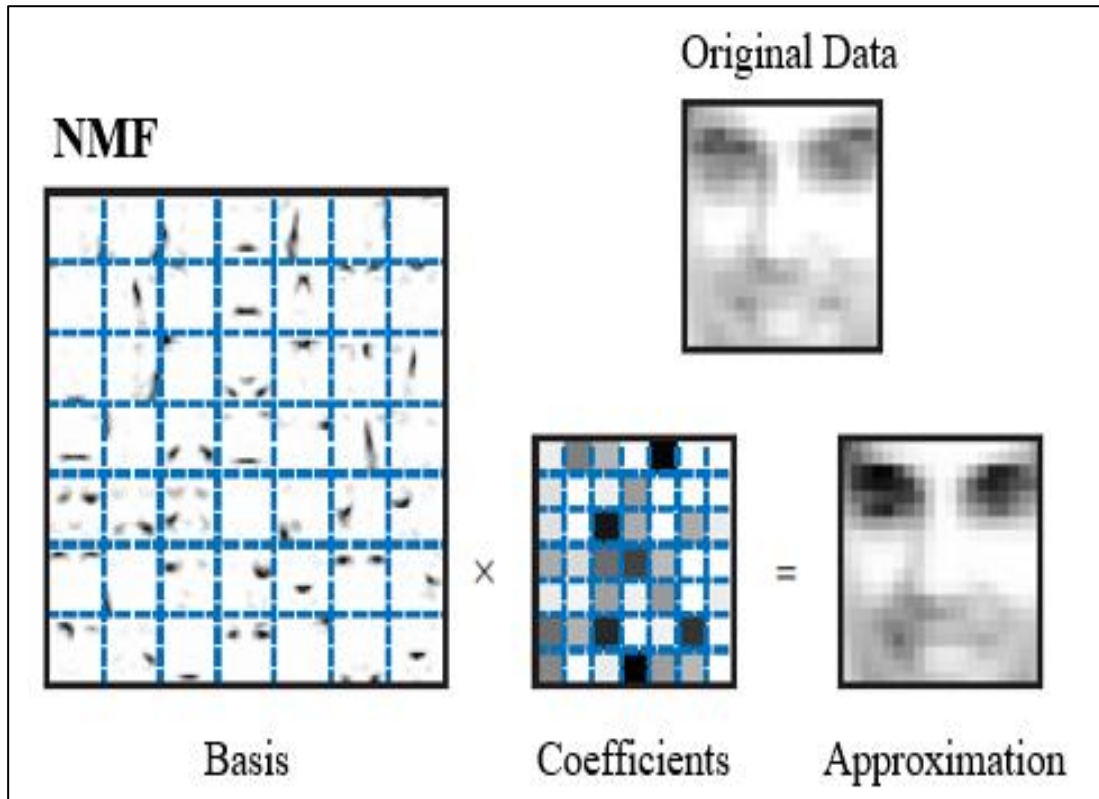
- a **basis matrix**  $W \in \mathbb{R}_+^{F \times K}$
- a **coefficient matrix**  $H \in \mathbb{R}_+^{K \times N}$

- $W = [w_{fk}]$  s.t.  $w_{fk} \geq 0$   
and
- $H = [h_{kn}]$  s.t.  $h_{kn} \geq 0$ .

**NMF** provides an unsupervised linear representation of the data

# Face Images by NMF

## Eigenfaces

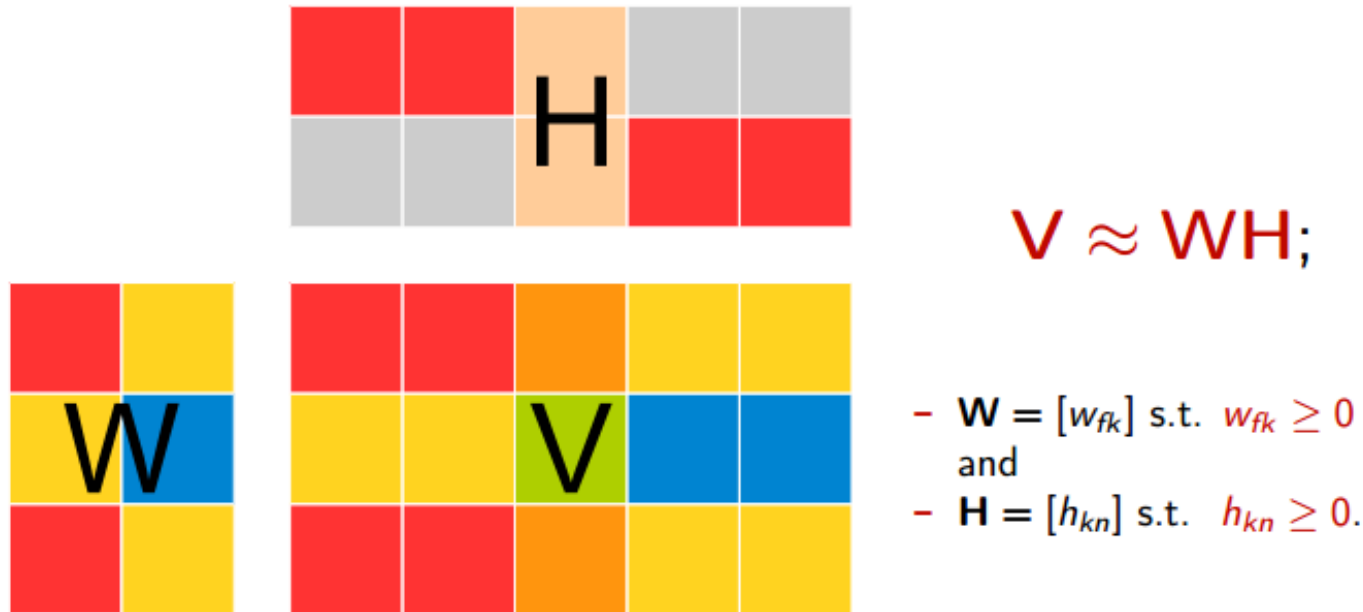


- ❑ Nonnegativity leads to **part-based decompositions** of object.
- ❑ Nonnegativity induces **sparsity**.

The work of **Lee and Seung (1999)** for “learning the parts-based representation of faces” has brought much attention to NMF in the data mining and machine learning field.

Figure from Lee and Seung (1999)

## Notation I



The standard NMF is usually formulated as an optimization:

$$\min_{W, H} D(V \| WH) \text{ s.t. } W \geq 0, H \geq 0$$

where  $D(V \| WH)$  is divergence function to measure the distance or error between  $V$  and  $WH$ .



## Notation II

There are two commonly used **divergence functions** that quantify the **error of the approximation** to solve NMF model.

### Euclidean distance (Frobenius norm)

$$D_{\text{Fro}}(V \| WH) = \|V - WH\|_F^2 = \sum_{i,j} \left( v_{ij} - \sum_{k=1}^k w_{ik} h_{kj} \right)^2$$

### Kullback-Leibler divergence

$$D_{\text{KL}}(V \| WH) = \sum_{i,j} \left( v_{ij} \log \frac{v_{ij}}{y_{ij}} - v_{ij} + y_{ij} \right)$$

where  $Y = [y_{ij}] = WH$ .



There are several algorithms that have been developed to solve the NMF problem

Multiplicative Update Rule Algorithm

Gradient Descent Algorithm

Alternating Least Squares Algorithm

Optimization methods of NMF produce a sequence of iterations

## Algorithm

### Multiplicative Update Rule of NMF with Frobenius norm

**Input:**  $V \in \mathbb{R}_{m \times n}$

**Output:**  $W \in \mathbb{R}_{m \times k}, H \in \mathbb{R}_{k \times n}$

**1: Initialize**

$$W^{(0)} \in \mathbb{R}_{m \times k} = \text{rand}(m, k)$$

$$H^{(0)} \in \mathbb{R}_{k \times n} = \text{rand}(k, n)$$

**2: for**  $t = 1:\text{maxiter}$

**3: Update**  $H_{kn}^{(t)} \leftarrow H_{kn}^{(t-1)} \frac{(W^{(t-1)T}V)_{kn}}{W_{kn}^{(t-1)T}(W^{(t-1)H})_{kn}}$

**4: Update**  $W_{mk}^{(t)} \leftarrow W_{mk}^{(t-1)} \frac{(VH^{(t-1)T})_{mk}}{(W^{(t-1)H})_{mk} H_{mk}^{(t-1)T}}$

**5: Convergence condition testing**

**6:  $t = t + 1$**

**7: end for**

Gradient descent algorithm apply the update rules using step size and the partial derivatives of objective function.

## Algorithm

### The Gradient Descent Algorithm of NMF

**Input:**  $V \in \mathbb{R}_{m \times n}$

**Output:**  $W \in \mathbb{R}_{m \times k}, H \in \mathbb{R}_{k \times n}$

#### 1: Initialize

$W^{(0)} \in \mathbb{R}_{m \times k} = \text{rand}(m, k)$

$H^{(0)} \in \mathbb{R}_{k \times n} = \text{rand}(k, n)$

#### 2: for t = 1: maxiter

3: Update  $H \leftarrow H - \beta_H \frac{\partial O}{\partial H}$

(nonneg) Set all negative elements in H to 0

4: Update  $W \leftarrow W - \beta_W \frac{\partial O}{\partial W}$

(nonneg) Set all negative elements in W to 0

5: Convergence condition testing

6:  $t = t + 1$

7: end for

The partial derivatives equation

$$\begin{aligned} O_{Fro\_NMF}(V \| WH) &= O_{Fro\_NMF}(W, H) \\ &= \|V - WH\|_F^2 \\ &= \text{Tr}(V - WH)^T (V - WH) \\ &= \text{Tr}(V^T V - 2H^T W^T V + H^T W^T W H) \end{aligned}$$

The gradient of the function  $O_{Fro\_NMF}(W, H)$

$$\begin{aligned} \nabla_W O_{Fro\_NMF}(W, H) &= \frac{\partial O}{\partial W} = -VH^T + WHH^T \\ \nabla_H O_{Fro\_NMF}(W, H) &= \frac{\partial O}{\partial H} = -W^T V + W^T W H \end{aligned}$$

The step size parameters  $\beta_W$  and  $\beta_H$  vary depending on the algorithm.

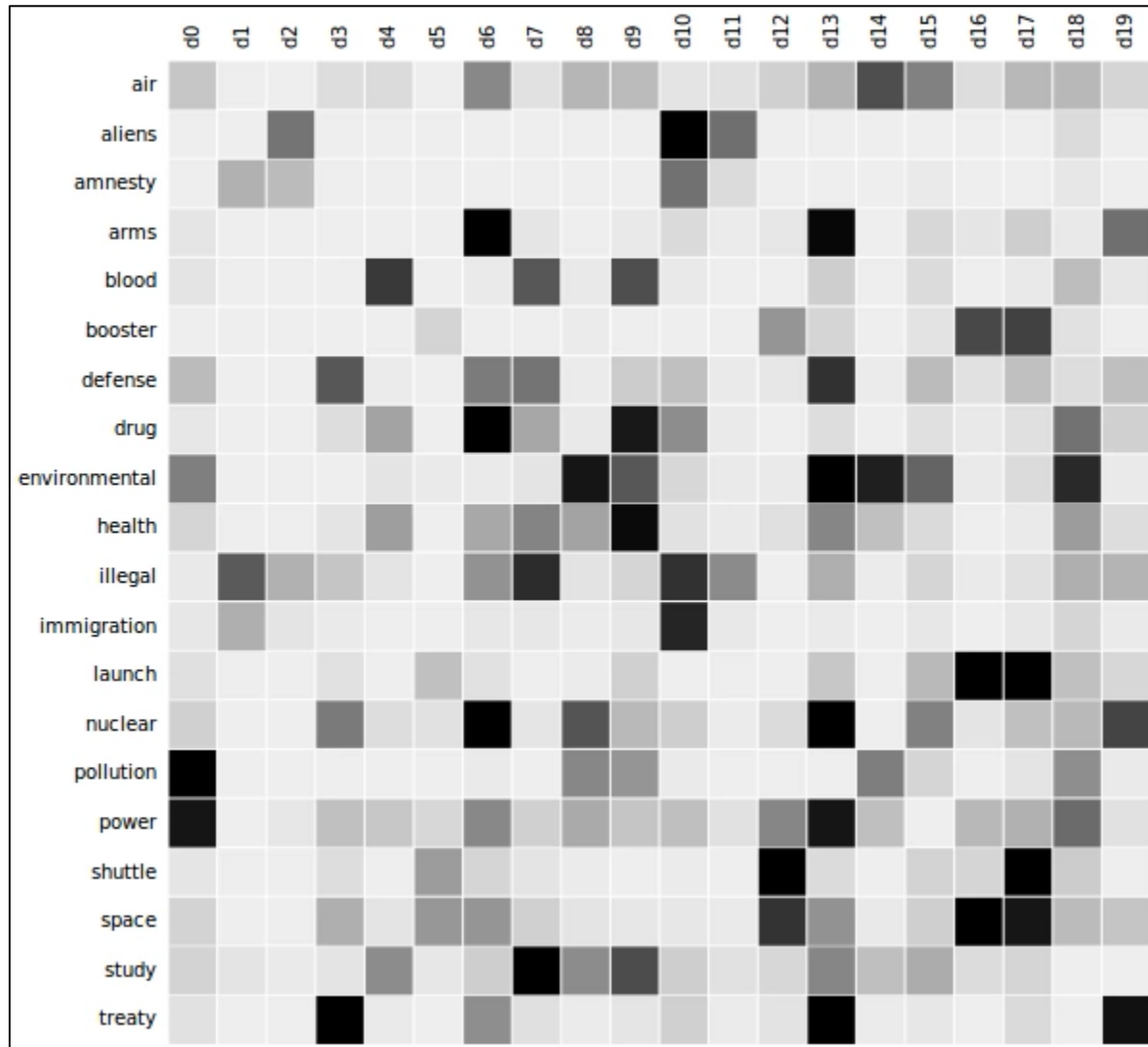


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# Application of Matrix Factorizations for Topic Modeling and Document Clustering



# Data Representation

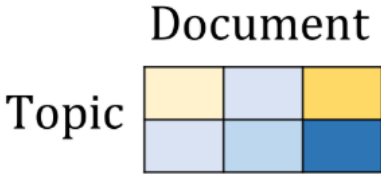
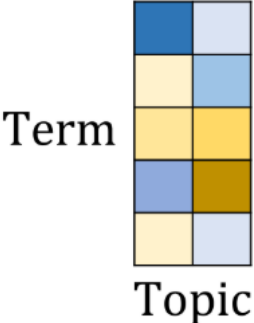
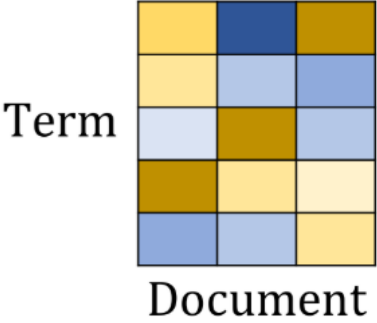


**Document-Term Matrix**

([https://en.wikipedia.org/wiki/Topic\\_model](https://en.wikipedia.org/wiki/Topic_model))

# Nonnegative Matrix Factorization for Topic Modeling and Document Clustering

$$V_{F \times N} \approx W_{F \times K} \times H_{K \times N}$$



**Document-Term Matrix**

	d_1	d_2	d_3
term_1	1	0	0
term_2	0	1	1
term_n	2	0	1

**Basis/Features Matrix**

	topic_1	topic_2
term_1	0.5	0
term_2	0	0.5
term_n	1	0

**Coefficient Matrix**

	d_1	d_2	d_3
topic_1	1	0	0
topic_2	0	1	1

# Matrix Factorization Methods for Topic Modeling and Document Clustering



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Non-negative Matrix  
Factorization (NMF)

Latent Dirichlet  
Allocation (LDA)

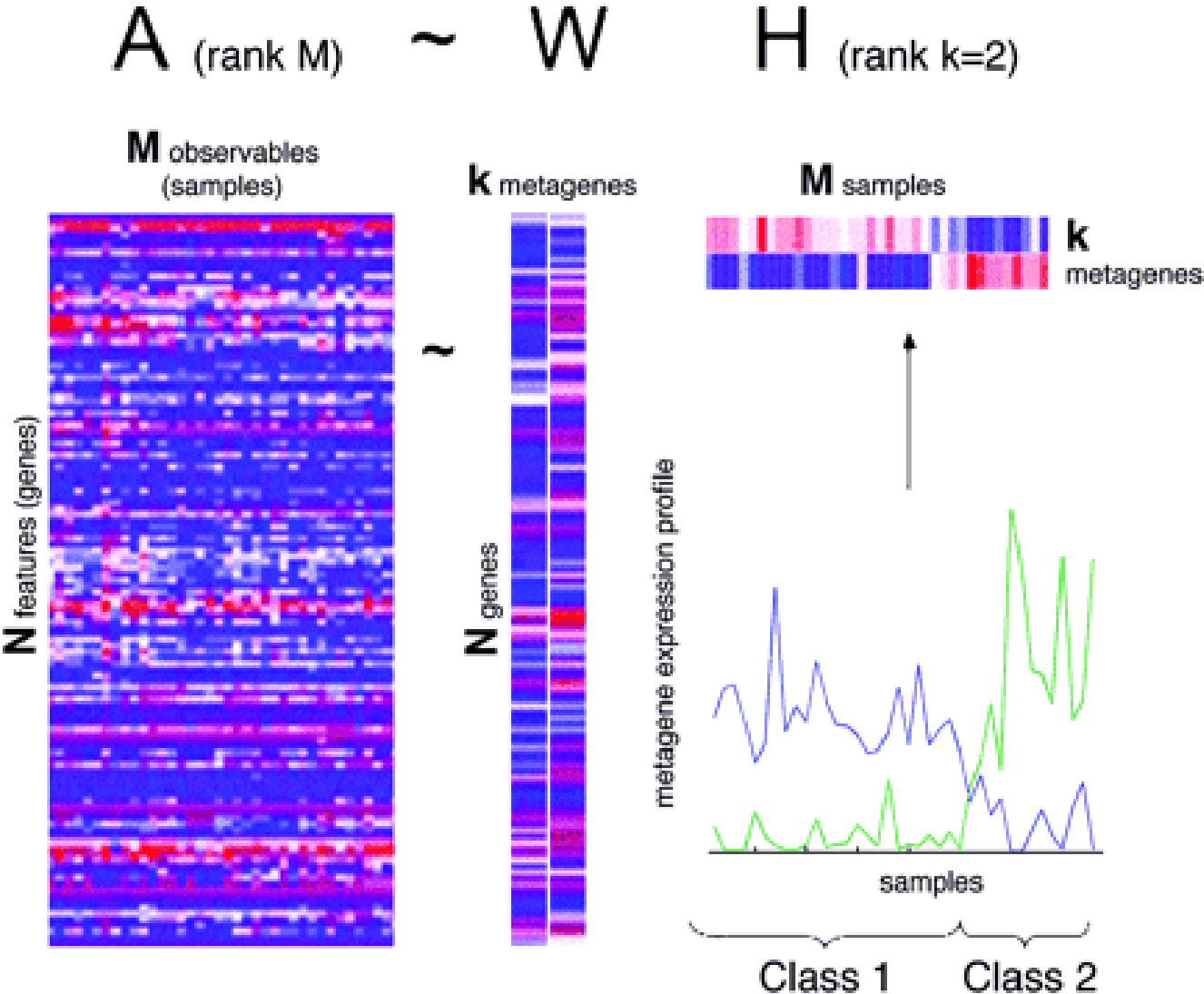
Singular Value  
Decomposition  
(SVD)



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# Applications of Matrix Factorizations for Gene Expression Analysis

# Nonnegative Matrix Factorization for Clustering Tumor Subtypes



# Matrix Factorization Methods for Clustering Tumor Subtypes

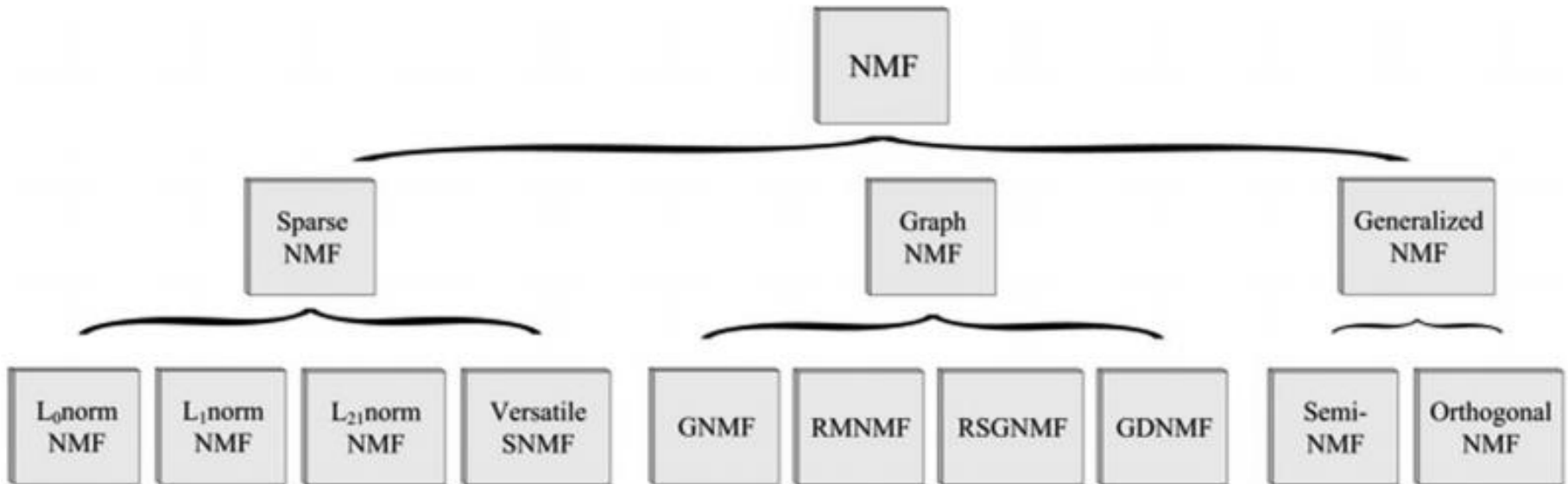


TABLE 4  
The Accuracy of Clustering on Leukemia Dataset

Number of types	samples	NMF	NMFL21	RMNMF	RSGNMF	GDNMF	GNMF	orth-NMF	K-means
K = 2	38	92.10%	<b>97.38%</b>	92.10%	86.84%	92.10%	92.10%	92.10%	94.70%
K = 3	38	86.84%	89.47%	92.10%	84.21%	92.10%	<b>94.83%</b>	84.21%	81.50%

<https://www.researchgate.net/publication/313454264>



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# Applications of Matrix Factorizations for Collaborative Filtering Recommendation System

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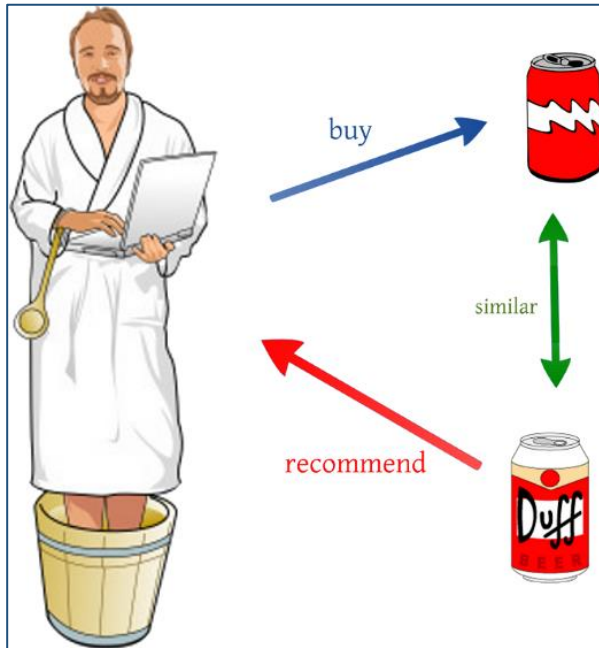
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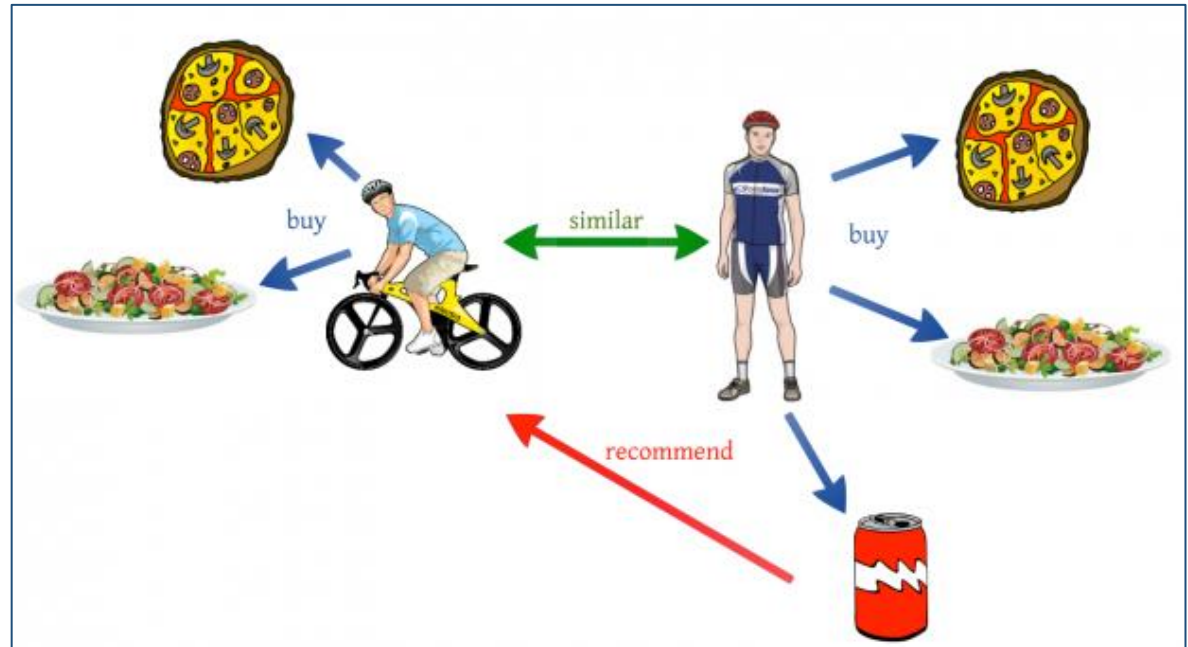
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# Recommender System Techniques



## Content-Based Filtering

recommend the item based on the similarity of item that highly rated by user before

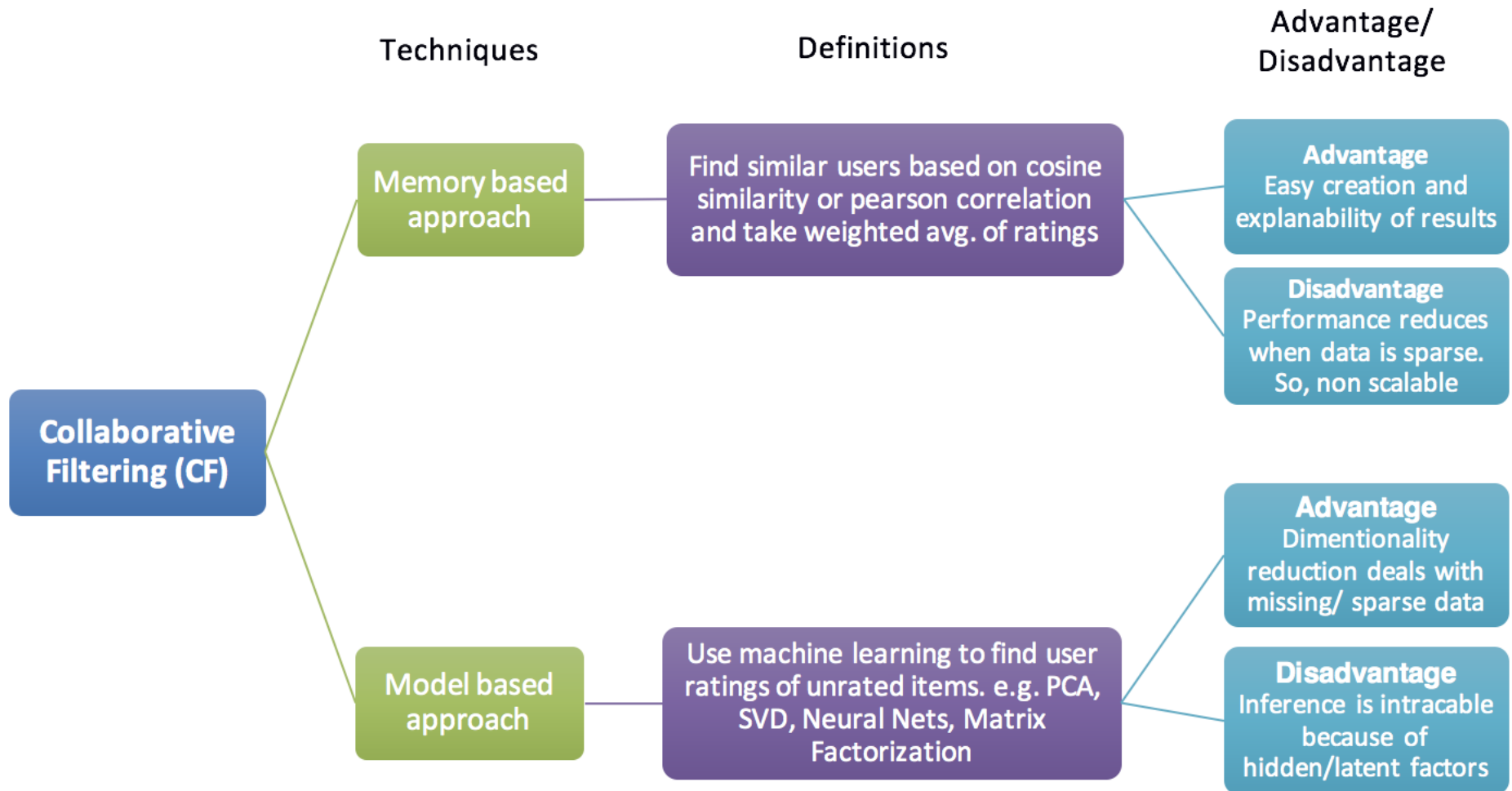


## Collaborative Filtering

recommend the item based on based on the idea that people who share the same interest in certain kind of items will also share the same interest in some other kind of items

<https://d4datascience.wordpress.com/2016/07/22/recommender-systems-101/>

# Collaborative Filtering Approaches

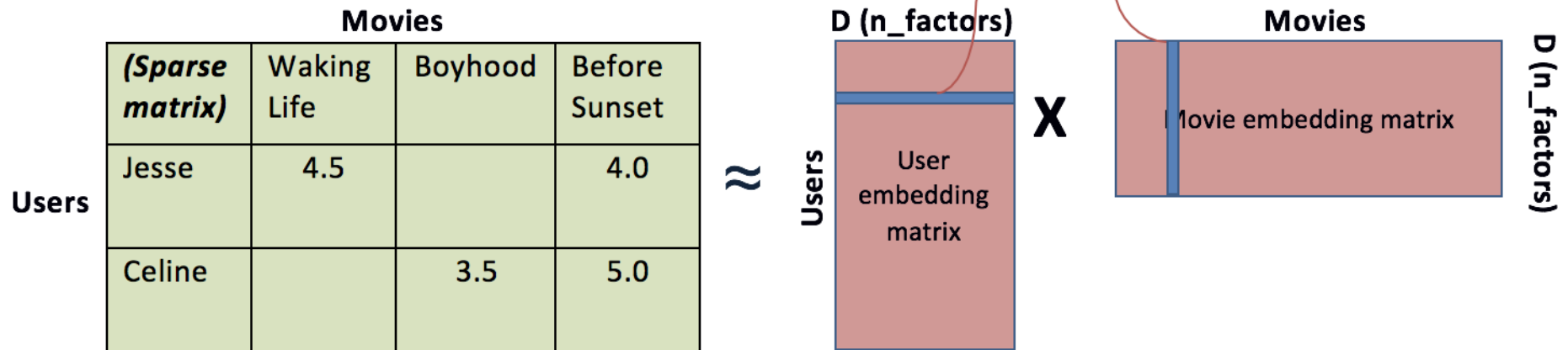


**Types of collaborative filtering approaches**

# Matrix Factorizations for Collaborative Filtering Recommendation System

$$V_{F \times N} \approx W_{F \times K} \times H_{K \times N}$$

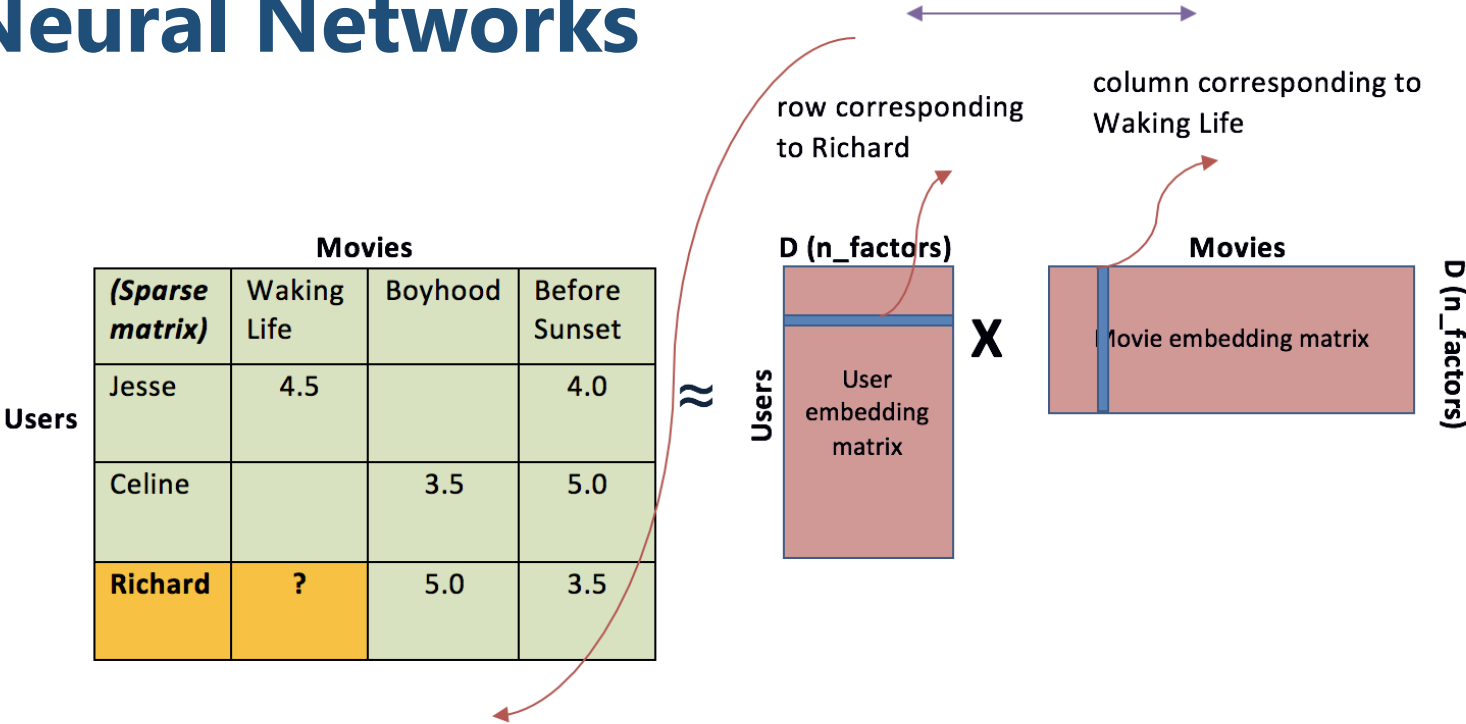
Dot product of Movie-A with User-X gives prediction for Movie-A by User-X



## Visualization of Matrix Factorization

Assumes that **latent factors** exist in user/movies

# Matrix factorization and Embeddings for Neural Networks



Linear and nonlinear layers  
 Input (X)  $\longrightarrow$  Target (Y)

Users	Movies
Jesse	Waking Life
Jesse	Boyhood
Jesse	Before Sunset
Celine	Waking Life
Celine	Boyhood
Celine	Before Sunset
<b>Richard</b>	<b>Waking Life</b>
Richard	Boyhood
Richard	Before Sunset

User latent features	Movie latent features
0.2, 0.4, 2.8, 4.8, 2.4	0.1, 0.5, 5.0, 3.7, 2.8
.....	....
.....	....
.....	....
.....	....
.....	....
<b>2.2, 1.4, 2, 1.8, 4.4</b>	<b>0.1, 0.25, 4.5, 3.1, 2</b>
.....	....
.....	....

Ratings
4.5
4.0
3.5
5.0
<b>?</b>
5.0
3.5

# Matrix Factorization Methods for Collaborative Filtering Recommendation System



Non-negative  
Matrix  
Factorization  
(NMF)

Probabilistic  
Matrix  
Factorization  
(PMF)

Singular Value  
Decomposition  
(SVD)

Principal  
Component  
Analysis (PCA)

Deep Matrix  
Factorization  
(DMF)



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# Applications of Matrix Factorizations for Image Processing

# Face Images by NMF

## Eigenfaces

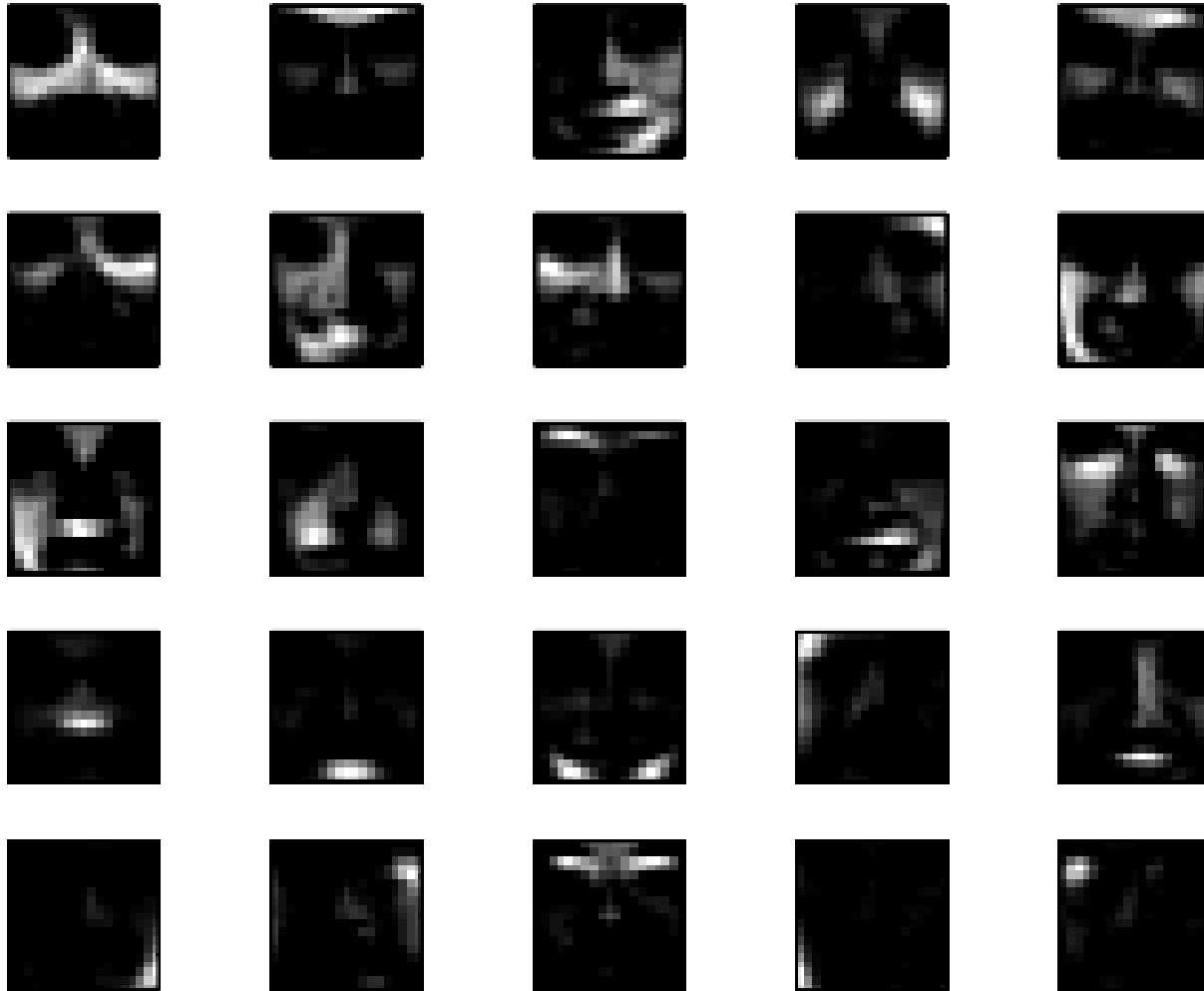


Illustration by C. Fevotte

# Image Reconstruction using Eigenfaces



Original images corrupted by occlusion from ORL dataset



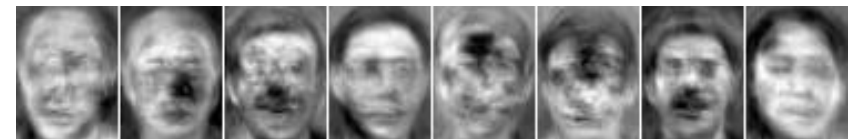
NMF\_EUD



GNMF



NMF\_KL



SpatialNMF



NMF\_PGd



CoupledNMF

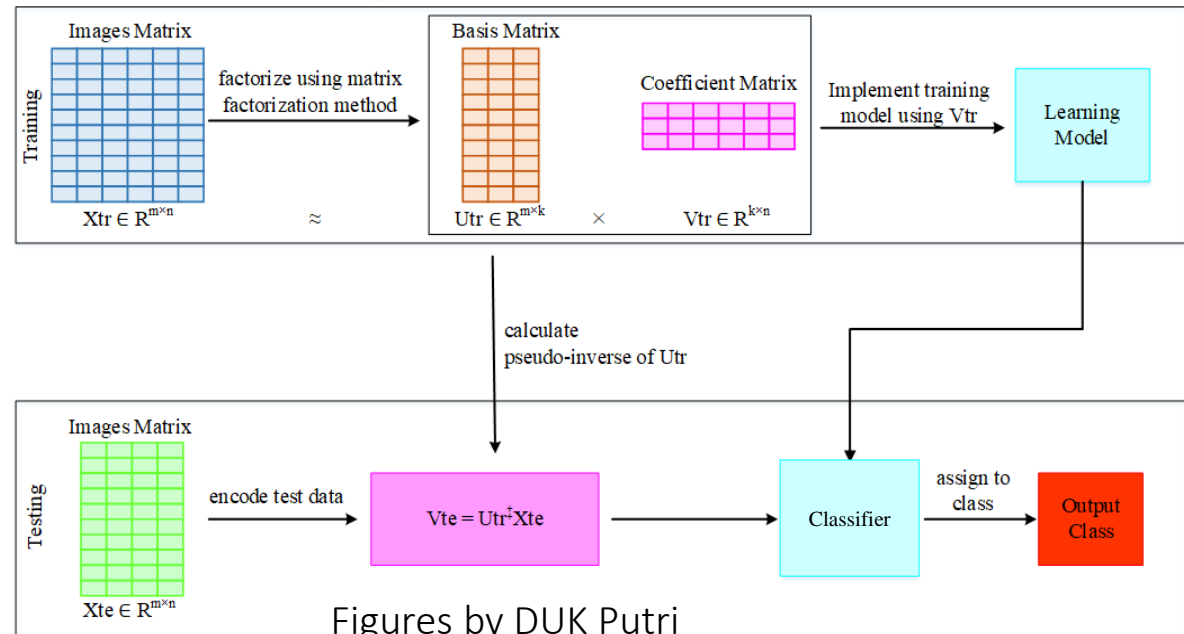
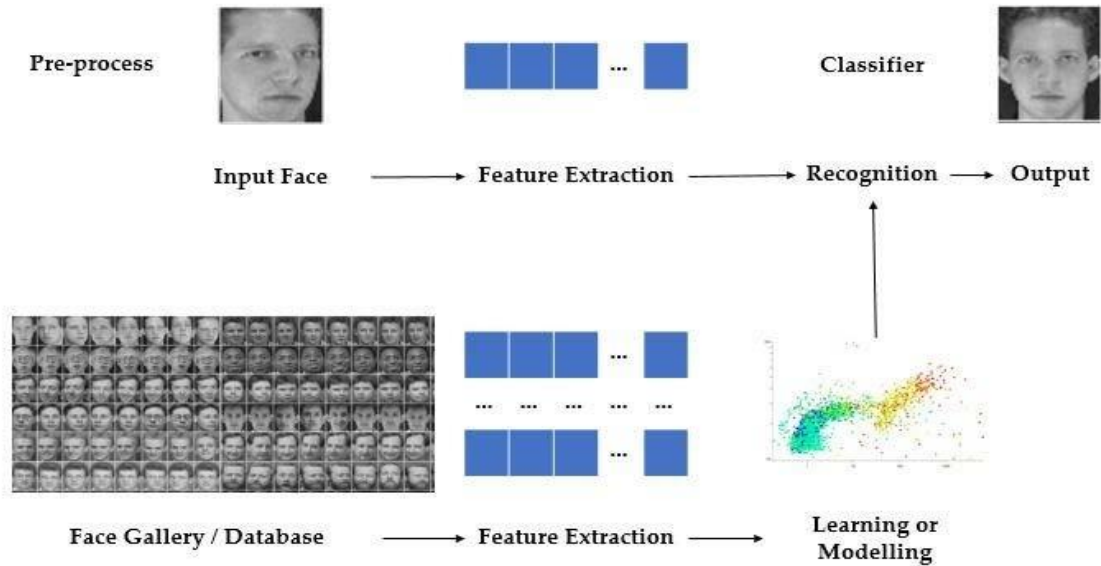


SNMF

Figures by DUK Putri



# Face Recognition



Figures by DUK Putri

Figures by DUK Putri



**CMF will be decomposed the complex-valued matrix into two matrices of bases and coefficients.**

- ❑ The real data matrix is transformed into a complex number based on the **Euler representation**
- ❑ *Wirtinger's* calculus is used to compute derivative of the cost function.
- ❑ The gradient descent method is used to solve complex matrix factorization problems.

- Let the input data matrix  $V = (V_1, V_2, \dots, V_N)$  contains  $N$  data vectors as columns.
- Using the **Euler's formula**, the elements of real matrix  $V$  are normalized and transformed into a complex number field to yield the complex data matrix  $Z$ .

The mapping function  $f: \mathbb{R}^M \rightarrow \mathbb{C}^M$  defined by:

$$Z_t = f(V_t) = \frac{1}{\sqrt{2}} e^{ia\pi V_t} = \frac{1}{\sqrt{2}} \begin{bmatrix} e^{ia\pi V_t(1)} \\ \vdots \\ e^{ia\pi V_t(M)} \end{bmatrix}$$

where the Euler's formula is

$$e^{ia\pi V_t} = \cos(a\pi V_t) + i \sin(a\pi V_t)$$

- The nonlinear function  $f$  is a special feature mapping which transform the real valued features to complex feature space.

## Notation I

- Given a matrix  $Z \in \mathbb{C}^{m \times n}$ , find two matrices  $W \in \mathbb{C}^{m \times k}$  and  $H \in \mathbb{C}^{k \times n}$  that minimize the objective function using Euclidean distance (Frobenius norm)

$$O_{\text{CMF}}(W, H) = \frac{1}{2} \|Z - WH\|_F^2$$

- These problem can be solved by using **block coordinate descent (BCD)** with two matrix block alternatingly to obtain a local solution

## Notation II

□ **With  $W$  fixed**, the optimization objective function is modified as follows

$$\min_H O(H) = \min_H \left( \frac{1}{2} \|Z - WH\|_F^2 \right)$$

□ To solve the subproblem, the one variable  $O(H)$  is treated as bivariable function  $O(H, H^*)$

$$O(H, H^*) = \frac{1}{2} \text{Tr}(Z^H Z - 2(H^*)^T W^H Z + (H^*)^T W^H W H)$$

□ The **gradient descent method** is utilized to update the current solution  $H^{(t)}$  to  $H^{(t+1)}$

$$H^{(t+1)} = H^{(t)} - \beta^{(t)} \nabla_{H^*} O(H^{(t)}, H^{*(t)})$$

□ where  $\beta^{(t)}$  is the step size. Backtracking line search (Armijo rule) is used to estimate step size

□ The first order partial derivative with respect to  $H^*$  for have the form

$$\nabla_{H^*} O(H, H^*) = -W^H Z + W^H W V$$

□ **With  $H$  fixed**, the update rule for obtaining  $W$  is  $W = H^\ddagger Z$ , where  $\ddagger$  denoted the Moore-Penrose pseudoinverse.

# Complex Matrix Factorization

## Stopping Condition



### Algorithm

#### Complex Gradient Descent Algorithm

Input:  $Z, H, 0 < \mu < 1, 0 < \sigma < 1$   
Output:  $H$   
1. Initialize any feasible  $H^{(0)}$   
Set  $\beta^{(0)} = 1$   
2. repeat  
(a) Compute gradient  $\nabla_{H^*} O(H^{(t)}, H^{*(t)})$   
(b) for  $t = 1, 2, \dots$   
    (b1) Assign  $\beta^{(t)} \leftarrow \beta^{(t-1)}$   
    (b2) if  $\beta^{(t)}$  satisfies  
        repeat  
             $\beta^{(t)} = \beta^{(t)} / \mu$   
        until either  $\beta^{(t)}$  does not satisfy  
            or  $H(\beta^{(t)} / \mu) = H(\beta^{(t)})$   
    else  
        repeat  
             $\beta^{(t)} = \beta^{(t)} \mu$   
        until  $\beta^{(t)}$  satisfies  
    (b3) set  $H^{(t+1)} = H^{(t)} - \beta^{(t)} \nabla_{H^*} O(H^{(t)}, H^{*(t)})$   
until Stopping criterion is satisfied

The **complex gradient descent (CGD) method** for optimizing the objective function.

An ideal criterion can be used to stop the iterative process when a **local minimum of the objective function is reached**.

The stopping condition is adapted by applying the follow condition

$$\|\nabla_{H^*} O(H)\|_F \leq \varepsilon$$

where  $\varepsilon$  is pre-defined threshold.



1

**Sparse Complex Matrix Factorization using Ridge Term (SCMF- $L_2$ )** which used  $L_2$ -norm regularization to provide smoothness of the coefficient matrix.

2

**Spatial Complex Matrix Factorization (SpatialCMF)** used spatial locality using pixel dispersion penalty to the basis matrix.

3

**Coupled Complex Matrix Factorization (CoupledCMF)** used combination of pixel images representation and class activity annotation

# Results of Face Recognition Rate



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un-occluded ORL dataset with different subspace dimensions

k	NMF_EUD	NMF_KL	NMF_PGD	CMF	SNMF	SCMF	SCMF-L <sub>2</sub>	GNMF	GCMF	Spatial NMF	Spatial CMF	Coupled NMF	Coupled CMF
10	0,8781± 0,0246	0,8720± 0,0242	0,8789± 0,0277	0,9194± 0,0258	0,8532± 0,0350	0,9216± 0,0250	0,9298± 0,0206	0,8913± 0,0284	0,9183± 0,0227	0,1373± 0,0684	0,9084± 0,0248	0,9412± 0,0879	<b>0,9933±</b> <b>0,0093</b>
20	0,9134± 0,0246	0,9081± 0,0234	0,9118± 0,0260	0,9398± 0,0181	0,9132± 0,0280	0,9437± 0,0177	0,9475± 0,0147	0,9212± 0,0255	0,9406± 0,0223	0,2708± 0,2533	0,9308± 0,0170	0,9657± 0,0417	<b>0,9892±</b> <b>0,0093</b>
30	0,9322± 0,0216	0,9307± 0,0176	0,9343± 0,0220	<b>0,9585±</b> <b>0,0188</b>	0,9242± 0,0236	0,9545± 0,0168	0,9601± 0,0148	0,9361± 0,0225	0,9552± 0,0166	0,9377± 0,0164	0,9444± 0,0237	0,9666± 0,0246	<b>0,9902±</b> <b>0,0053</b>
40	0,9334± 0,0247	0,9349± 0,0223	0,9376± 0,0218	0,9548± 0,0196	<b>0,9315±</b> <b>0,0203</b>	<b>0,9567±</b> <b>0,0167</b>	<b>0,9619±</b> <b>0,0199</b>	0,9388± 0,0169	<b>0,9585±</b> <b>0,0174</b>	0,9392± 0,0232	0,9488± 0,0167	0,9767± 0,0109	<b>0,9875±</b> <b>0,0075</b>
50	<b>0,9390±</b> <b>0,0140</b>	<b>0,9362±</b> <b>0,0190</b>	<b>0,9400±</b> <b>0,0195</b>	0,9510± 0,0169	0,9288± 0,0188	0,9546± 0,0178	0,9600± 0,0132	0,9453± 0,0198	0,9507± 0,0209	0,9459± 0,0194	0,9430± 0,0215	<b>0,9785±</b> <b>0,0101</b>	<b>0,9860±</b> <b>0,0039</b>
60	0,9371± 0,0204	0,9276± 0,0227	0,9362± 0,0185	0,9535± 0,0191	0,9288± 0,0227	0,9529± 0,0173	0,9609± 0,0168	0,9456± 0,0190	0,9567± 0,0182	0,9470± 0,0149	0,9431± 0,0213	0,9773± 0,0078	<b>0,9860±</b> <b>0,0051</b>
70	0,9330± 0,0238	0,9358± 0,0152	0,9285± 0,0210	0,9517± 0,0206	0,9270± 0,0224	0,9501± 0,0222	0,9607± 0,0114	0,9397± 0,0203	0,9498± 0,0184	0,9470± 0,0131	<b>0,9502±</b> <b>0,0187</b>	0,9776± 0,0109	<b>0,9855±</b> <b>0,0059</b>
80	0,9322± 0,0207	0,9354± 0,0197	0,9225± 0,0263	0,9522± 0,0172	0,9306± 0,0197	0,9483± 0,0178	0,9614± 0,0119	0,9507± 0,0204	0,9517± 0,0171	<b>0,9535±</b> <b>0,0134</b>	0,9385± 0,0221	0,9780± 0,0084	<b>0,9850±</b> <b>0,0062</b>
90	0,9317± 0,0247	0,9232± 0,0192	0,9386± 0,0184	0,9533± 0,0140	0,9218± 0,0223	0,9505± 0,0154	0,9616± 0,0118	<b>0,9525±</b> <b>0,0150</b>	0,9512± 0,0199	0,9464± 0,0166	0,9443± 0,0151	0,9775± 0,0093	<b>0,9835±</b> <b>0,0075</b>
100	0,9332± 0,0247	0,9194± 0,0245	0,9229± 0,0203	0,9509± 0,0168	0,9270± 0,0244	0,9477± 0,0152	0,9613± 0,0162	0,9525± 0,0148	0,9496± 0,0200	0,9473± 0,0175	0,9424± 0,0238	0,9774± 0,0107	<b>0,9829±</b> <b>0,0075</b>
AVG	0,9263	0,9223	0,9251	0,9485	0,9186	0,9481	0,9565	0,9374	0,9482	0,7972	0,9394	0,9717	<b>0,9869</b>
MAX	0,9390	0,9362	0,9400	0,9585	0,9315	0,9567	0,9619	0,9525	0,9585	0,9535	0,9502	0,9785	<b>0,9933</b>

Results of research by DUK Putri



# Results of Face Recognition Rate



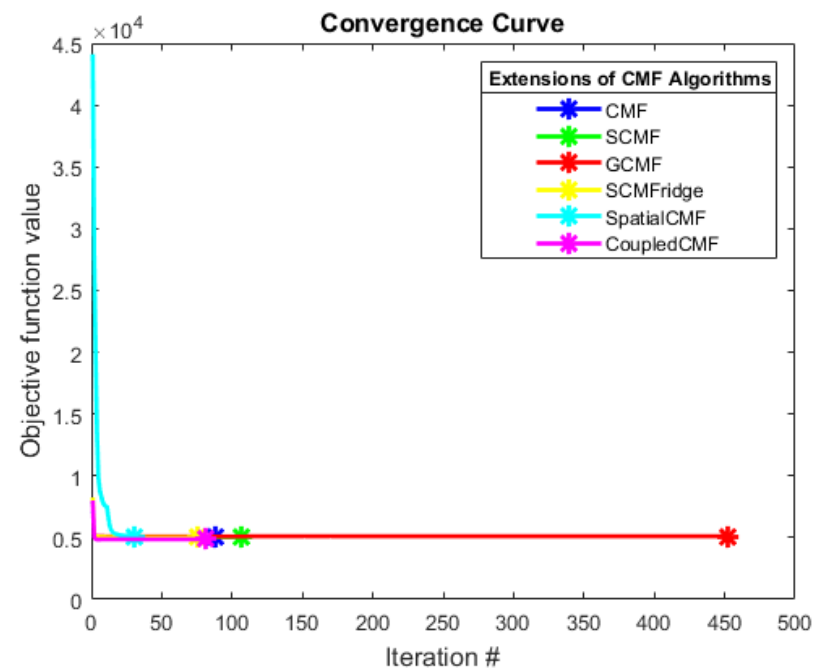
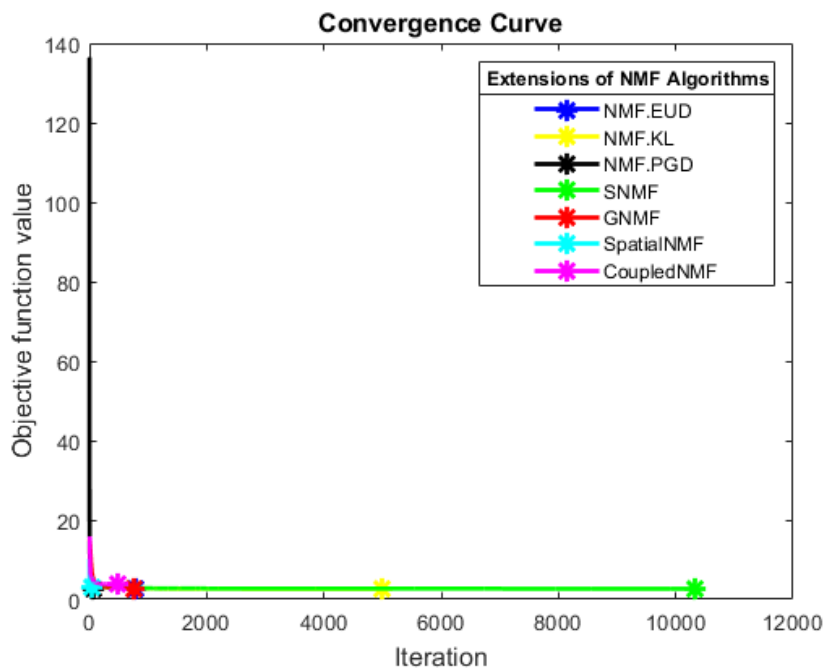
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## Occluded ORL dataset with different Patch Sizes

Patch	NMF_EUD	NMF_KL	NMF_PGD	CMF	SNMF	SCMF	SCMF-L <sub>2</sub>	GNMF	GCMF	Spatial NMF	Spatial CMF	Coupled NMF	Coupled CMF
15x15	0,8296±	0,8366±	0,8314±	0,9314±	0,8157±	0,9319±	0,9444±	0,8610±	0,9320±	0,8456±	0,9176±	0,9823±	<b>0,9872±</b>
	0,0270	0,0303	0,0325	0,0181	0,0263	0,0275	0,0208	0,0239	0,0181	0,0370	0,0267	0,0091	<b>0,0050</b>
20x20	0,6340±	0,6510±	0,6461±	0,8736±	0,6371±	0,8650±	0,8794±	0,7086±	0,8605±	0,6641±	0,8513±	0,9836±	<b>0,9882±</b>
	0,0368	0,0462	0,0339	0,0234	0,0398	0,0210	0,0296	0,0296	0,0267	0,0386	0,0390	0,0089	<b>0,0074</b>
25x25	0,4090±	0,4380±	0,4173±	0,7009±	0,4225±	0,6946±	0,7202±	0,4922±	0,6889±	0,4492±	0,6858±	0,9880±	<b>0,9925±</b>
	0,0335	0,0307	0,0347	0,0311	0,0567	0,0426	0,0389	0,0555	0,0392	0,0525	0,0528	0,0115	<b>0,0052</b>
30x30	0,2972±	0,3291±	0,3118±	0,5501±	0,3044±	0,5397±	0,5525±	0,3513±	0,5346±	0,3312±	0,5063±	0,9878±	<b>0,9915±</b>
	0,0379	0,0359	0,0457	0,0489	0,0361	0,0355	0,0373	0,0378	0,0404	0,0457	0,0553	0,0105	<b>0,0043</b>
AVG	0,5425	0,5637	0,5517	0,7640	0,5449	0,7578	0,7741	0,6033	0,7540	0,5725	0,7403	0,9854	0,9899

Results of research by DUK Putri

# Convergence Curves of Extensions of NMF and CMF Algorithms



Figures by DUK Putri

# Various Research for NMF Applications



## ❑ Text mining:

- ❑ (Xu et al., 2003; Berry and Browne, 2006; Kim and Park, 2008)

## ❑ Images:

- ❑ unsupervised object discovery (Sivic et al., 2005)
- ❑ object and face recognition (Soukup and Bajla, 2008)
- ❑ tagging (Kalayeh et al., 2014)
- ❑ denoising and inpainting (Mairal et al., 2010)
- ❑ texture classification (Sandler and Lindenbaum, 2011)
- ❑ spectral data (Berry et al.)
- ❑ hashing (Monga and Mihcak, 2007)
- ❑ watermarking (Lu et al., 2009)

## ❑ Electroencephalography (EEG) data:

- ❑ feature extraction (Cichocki and Rutkowski, 2006; Lee et al., 2009)
- ❑ artifact rejection (Damon et al., 2013a,b)

<https://www.cs.rochester.edu/u/jliu/CSC-576/NMF-tutorial.pdf>

# Various Research for NMF Applications



## □ Audio and music processing

- Source separation (speech) (Virtanen, 2007; Virtanen and Cemgil, 2009; Mohammadiha et al., 2013)
- Source separation (music) (Durrieu et al., 2009; Ozerov and Fevotte, 2010; Hennequin et al., 2011; Ozerov et al., 2013; Rafii et al., 2013)
- Signal enhancement/denoising (Wilson et al., 2008; Schmidt et al., 2007; Sun and Mazumder, 2013)
- Audio inpainting (Roux et al., 2011; Yilmaz et al., 2011)
- Compression (Ozerov et al., 2011b; Nikunen et al., 2011)
- Music transcription (Smaragdis and Brown, 2003; Abdallah and Plumbley, 2004; Vincent et al., 2007; E. Vincent et al., 2008; Févotte et al., 2009; Bertin et al., 2010; Vincent et al., 2010)

<https://www.cs.rochester.edu/u/jliu/CSC-576/NMF-tutorial.pdf>

# Various Research for NMF Applications



## ❑ Video processing

- ❑ Video summarization (Cooper and Foote, 2002)
- ❑ Dynamic video content representation and scene change detection (Bucak and Gunsels, 2007)
- ❑ Onscreen person spotting and shot-type classification (Essid and Fevotte, 2012, 2013)
- ❑ Fingerprinting (Cirakman et al., 2010)
- ❑ Action recognition (Krausz and Bauckhage, 2010; Masurelle et al., 2014)
- ❑ Compression (Türkan and Guillemot, 2011)

<https://www.cs.rochester.edu/u/jliu/CSC-576/NMF-tutorial.pdf>

# Various Research for NMF Applications



## ❑ Bioinformatics:

- ❑ gene expression analysis (Brunet et al., 2004; Gao and Church, 2005)
- ❑ protein interaction clustering (Greene et al., 2008)

## ❑ Other:

- ❑ collaborative filtering (Melville and Sindhwa, 2010)
- ❑ community discovery (Wang et al., 2010)
- ❑ portfolio diversification (Drakakis et al., 2007)
- ❑ food consumption analysis (Zetlaoui et al., 2010)
- ❑ industrial source apportionment (Limem et al., 2013)

<https://www.cs.rochester.edu/u/jliu/CSC-576/NMF-tutorial.pdf>



THANK YOU

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